

Simple stability criteria for nonlinear time-varying discrete systems

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Abstract: We present two sufficient conditions for asymptotic stability of nonlinear time-varying discrete systems. Our main results generalize Mori's result for linear discrete time-invariant systems to nonlinear time-varying systems.

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Introduction

Mori et al. [1] gave a delay independent stability condition for linear discrete systems. The system

$$x(n+1) = Ax(n) + Bx(n-h),$$

where $x \in \mathbb{R}^n$, A and $B \in \mathbb{R}^{n \times n}$, is asymptotically stable if

$$\|A\| + \|B\| < 1.$$

This result provides a simple way of stability check without solving characteristic roots. For nonlinear systems, a similar condition can be derived.

Main theorem. Consider a nonlinear discrete time-varying system of the following form:

$$x(n+1) = \sum_{i=1}^p A_i(\cdot, \cdot) x(n-h_i), \quad (1)$$

where $x \in \mathbb{R}^n$, $A_i(\cdot, \cdot) \in \mathbb{R}^{n \times n}$ is a function of time indices $n, n-1, n-2, \dots$, etc., and $x(n), x(n-1)$,

$x(n-2), \dots$, etc., and $0 \leq h_1 < h_2 < h_3 < \dots < h_p$. Suppose there exists operator norm $\|\cdot\|$ and constants $C_i > 0$, $1 \leq i \leq p$ such that

$$\|A_i(\cdot, \cdot)\| \leq c_i.$$

Then system (1) is asymptotically stable if

$$\sum_{i=1}^p c_i < 1.$$

Lemma 1. Consider the following scalar difference equation:

$$y(n+1) = a_1 y(n-h_1) + a_2 y(n-h_2) + \dots + a_p y(n-h_p), \quad (2)$$

where $y(n) \geq 0$ and $a_i \geq 0$.

Then

$$\sum_{i=1}^p a_i < 1 \Leftrightarrow y(n) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Proof. (\Rightarrow) Suppose $\sum_{i=1}^p a_i < 1$. By applying z -transform to equation (2), the characteristic polynomial is

$$H(z) = z^{h_p+1} - a_1 z^{(h_p-h_1)} - a_2 z^{(h_p-h_2)} - \dots - a_p.$$

Let

$$H_1(z) = z^{h_p+1}, \text{ and}$$

$$H_2(z) = -(a_1 z^{(h_p-h_1)} + \dots + a_p).$$

Then $\forall z, |z| = 1$, we have

$$|H_1(z)| = 1 \text{ and}$$

$$|H_2(z)| \leq a_1 + a_2 + \dots + a_p < 1.$$

Hence,

$$|H_1(z)| > |H_2(z)|.$$

By Rouché Theorem [2] H_1 and $H_1 + H_2$ have same number of roots (counting multiplicity) inside

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the unit circle. Therefore, all roots of $H(z) = H_1(z) + H_2(z)$ are inside the unit circle and the solution of equation (2) asymptotically converges to zero.

(\Leftarrow) Suppose $\sum_{i=1}^p a_i \geq 1$.

(i) $\sum a_i = 1 \Rightarrow H(1) = 0 \Rightarrow$ equation (2) is not asymptotically stable.

(ii) $\sum a_i > 1$. Then $H(1) = 1 - \sum_{i=1}^p a_i < 0$.

Choose a number b sufficiently large such that $H(b) > 0$; then $H(1)H(b) < 0$, which implies that there exists $e, 1 < e < b$, such that $H(e) = 0$. Therefore, the system is unstable.

Lemma 2. Consider the following scalar difference inequality:

$$w(n+1) \leq a_1 w(n-h_1) + a_2 w(n-h_2) + \dots + a_p w(n-h_p), \quad (3)$$

where $w(n) \geq 0, a_i \geq 0$.

If (2) and (3) have same initial condition, then $w(n) \leq y(n)$ for $n = 1, 2, \dots$

Proof. Suppose there exists a positive integer m such that

$$w(k) \leq y(k), \quad k \leq m \text{ and } w(m+1) > y(m+1).$$

Since

$$w(m+1) \leq \sum_{i=1}^p a_i w(m-h_i),$$

$$y(m+1) = \sum_{i=1}^p a_i y(m-h_i),$$

imply $w(m+1) \leq y(m+1)$, it contradicts (3). Hence the proof is complete. \square

Therefore, by Lemmas 1 and 2, we can conclude that

$$w(n) \rightarrow 0 \text{ as } n \rightarrow \infty$$

if

$$y(n) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Proof of main theorem. Since equation (1) can be expressed as

$$x(n+1) = \sum_{i=1}^p A_i(\cdot, \cdot) x(n-h_i) \quad (4)$$

and $\|A_i(\cdot, \cdot)\| \leq c_i$, taking norm on both sides of equation (4) yields

$$\begin{aligned} \|x(n+1)\| &= \left\| \sum_{i=1}^p A_i(\cdot, \cdot) x(n-h_i) \right\| \\ &\leq \sum_{i=1}^p \|A_i(\cdot, \cdot)\| \|x(n-h_i)\| \\ &\leq \sum_{i=1}^p c_i \|x(n-h_i)\|. \end{aligned}$$

By Lemmas 1 and 2, $\|x(n)\| \rightarrow 0$ as $n \rightarrow \infty$.

Corollary. Suppose

$$x(n+1) = \sum_{i=1}^p f_i(\cdot, x(n-h_i)), \quad (5)$$

where $x \in \mathbb{R}^n, 0 \leq h_1 < h_2 < h_3 \dots < h_p$, and $f_i: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is C^1 function of x , which may vary with time and $f(\cdot, 0) = 0$.

Suppose there is an operator norm such that for every $x \in \mathbb{R}^n$

$$\|Jf_i(\cdot, x)\| \leq c_i$$

($Jf_i(\cdot, x)$ is the Jacobian matrix of f_i at x)

then equation (5) is asymptotically stable if $\sum_{i=1}^p c_i < 1$.

Proof. $\forall x \in \mathbb{R}^n$,

$$\begin{aligned} f_i(\cdot, x) &= f_i(\cdot, x) - f_i(\cdot, 0) = \int_0^1 \left[\frac{d}{d\lambda} f_i(\cdot, \lambda x) \right] d\lambda \\ &= \int_0^1 [Jf_i(\cdot, \lambda x)] x d\lambda = A_i(\cdot, x)x, \end{aligned}$$

where

$$A_i(\cdot, x) = \int_0^1 Jf_i(\cdot, \lambda x) d\lambda.$$

Further,

$$\|A_i(\cdot, x)\| = \int_0^1 \|Jf_i(\cdot, \lambda x)\| d\lambda \leq c_i.$$

The proof is completed by applying the main theorem.

The result of Mori et al. [1] is a special case of the main theorem or of the Corollary, supposing $f_i(x) = A_i x$.

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Example 1. Consider

$$x(n+1) = \begin{bmatrix} x_1(n+1) \\ x_2(n+1) \end{bmatrix} = \begin{bmatrix} 0.5 \cos(n) \sin(x_1(n-5)) x_2(n) \\ 0.4 \cos(x_1(n)) x_2(n-10) \end{bmatrix}$$

Then

$$A_1(\cdot, \cdot)x(n) = \begin{bmatrix} 0 & 0.5 \cos(n) \sin(x_1(n-5)) \\ 0 & 0 \end{bmatrix} \times \begin{bmatrix} x_1(n) \\ x_2(n) \end{bmatrix}$$

$$A_2(\cdot, \cdot)x(n-10) = \begin{bmatrix} 0 & 0 \\ 0 & 0.4 \cos(x_1(n)) \end{bmatrix} \times \begin{bmatrix} x_1(n-10) \\ x_2(n-10) \end{bmatrix}$$

Then $\forall x \in \mathbb{R}^n$,

$$\|A_1(\cdot, \cdot)\|_\infty \leq c_1 = 0.5, \|A_2(\cdot, \cdot)\|_\infty \leq c_2 = 0.4.$$

Since $c_1 + c_2 = 0.9 < 1$, by the main theorem, $x(n)$ converges to 0 asymptotically.

Example 2. Consider

$$x(n+1) = \sin(n)[0.5 x(n) - 0.4 \sin(x(n-10))].$$

Since $f_1(\cdot, 0) = f_2(\cdot, 0) = 0$, $Jf_1(\cdot, x) = 0.5 \sin(n)$ and $Jf_2(\cdot, x) = 0.4 \sin(n) \cos(x(n-10))$ by the Corollary, $x(n)$ converges to 0 asymptotically.

Concluding remark

Simple delay-independent sufficient conditions for asymptotic stability of nonlinear time-varying discrete systems have been presented.

References

- [1] T. Mori, N. Fukuma and M. Kuwahara, Delay-independent stability criteria for discrete-delay systems, *IEEE Trans. Automat. Control* 27 (1982) 964-966.
- [2] W. Rudin, *Real and Complex Analysis* (McGraw-Hill, New York, 1974).

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