

# *Integer-N and Fractional-N Synthesizers*

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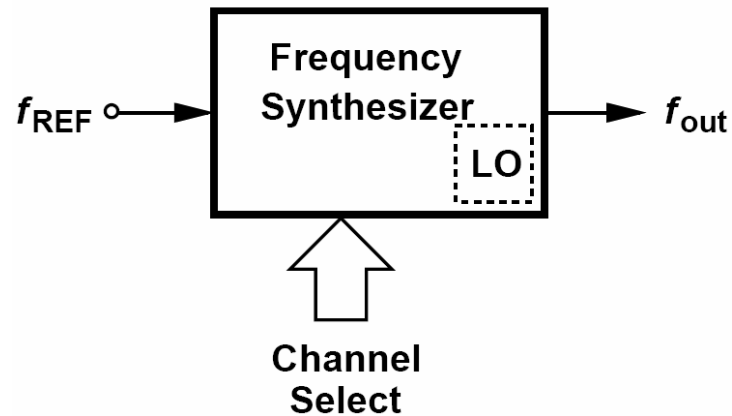
# Outline

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- **General Synthesizer Requirements**
- **Integer-N Synthesizers**
- **Basic Fractional-N Synthesizer**
- **Randomization and Noise Shaping**

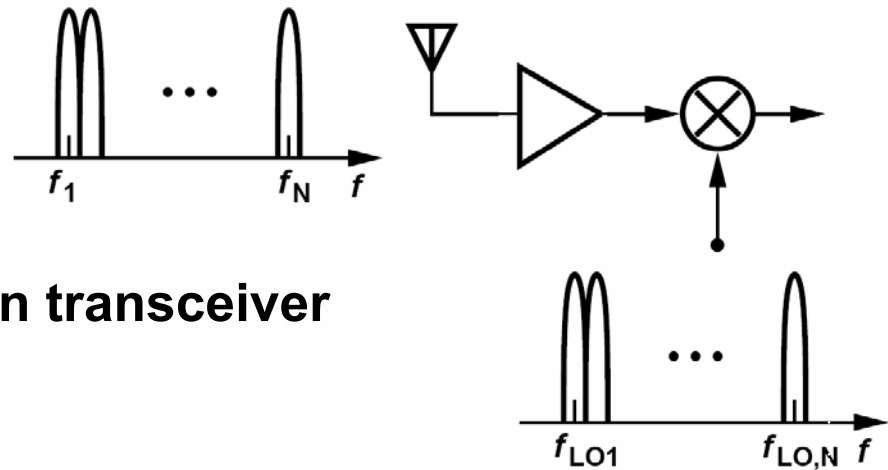
# General Considerations

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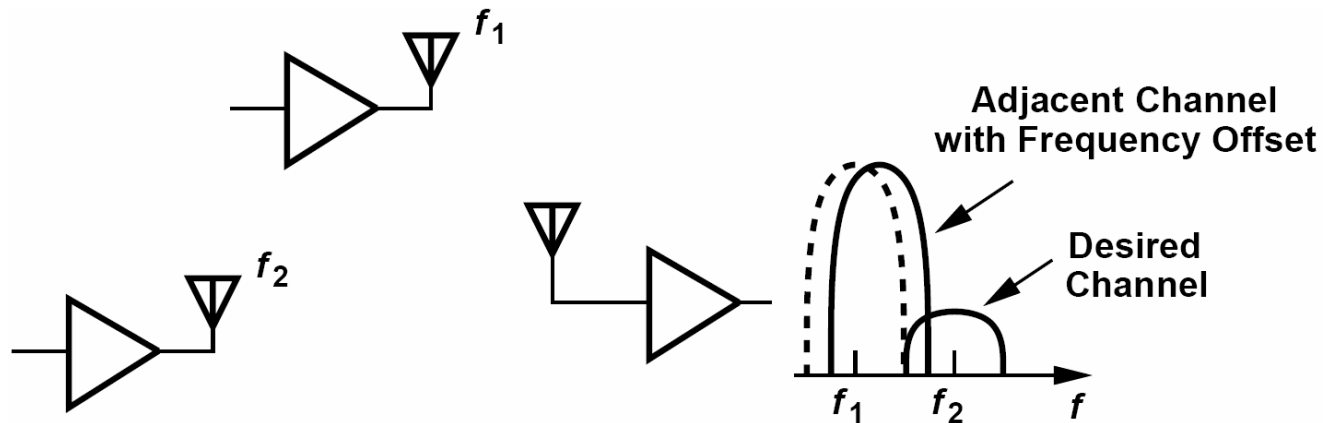


- **Channel Spacing**
- **Frequency Accuracy**
- **Phase Noise**
- **Sidebands (Spurs)**
- **Lock Time**
- **Power Dissipation**

# Channel Spacing and Frequency Accuracy



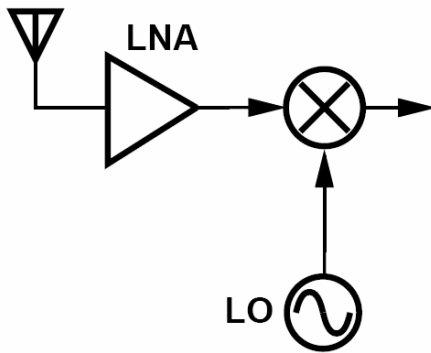
- Channel spacing depends on transceiver architecture.



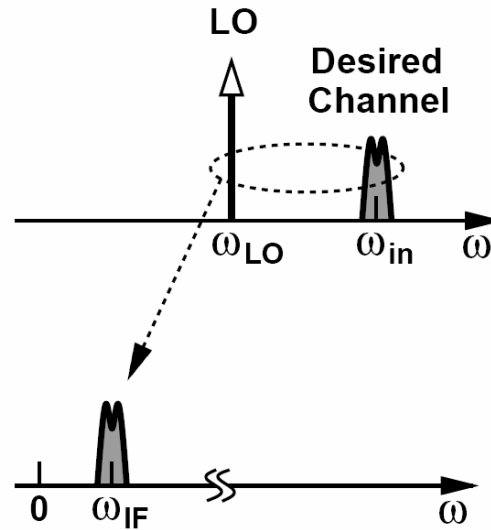
- Slight shift leads to significant spillage of high-power interferer.

# Phase Noise

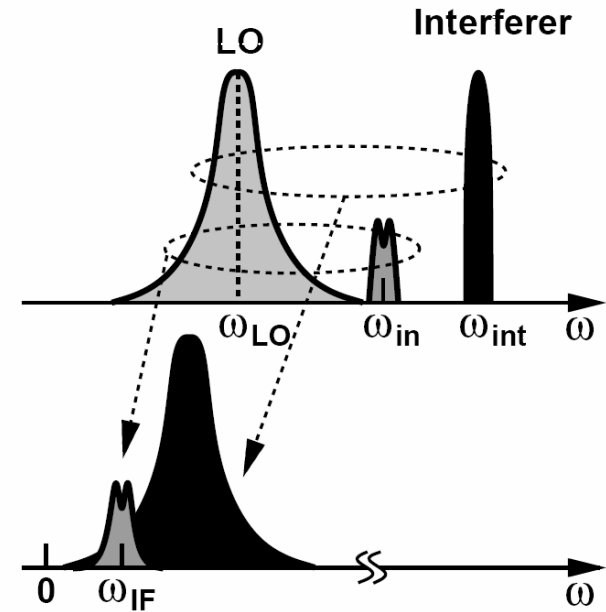
## Reciprocal Mixing:



### Ideal Case



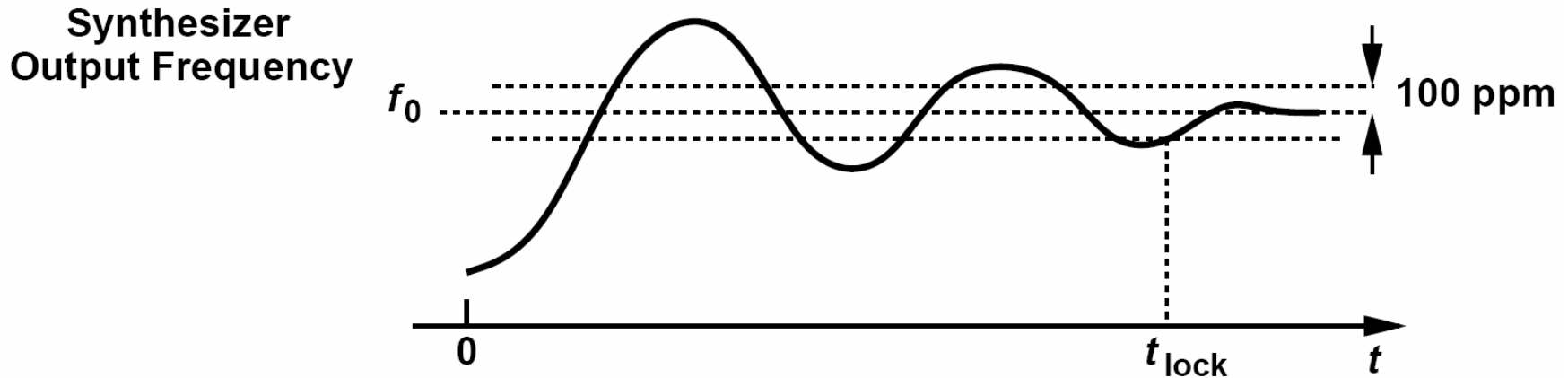
### Actual Case



## Corruption of Signal:

$$x_{QPSK}(t) = A \cos \left[ \omega_c t + (2k + 1) \frac{\pi}{4} + \phi_n(t) \right] \quad k = 0, \dots, 3$$

# Lock Time



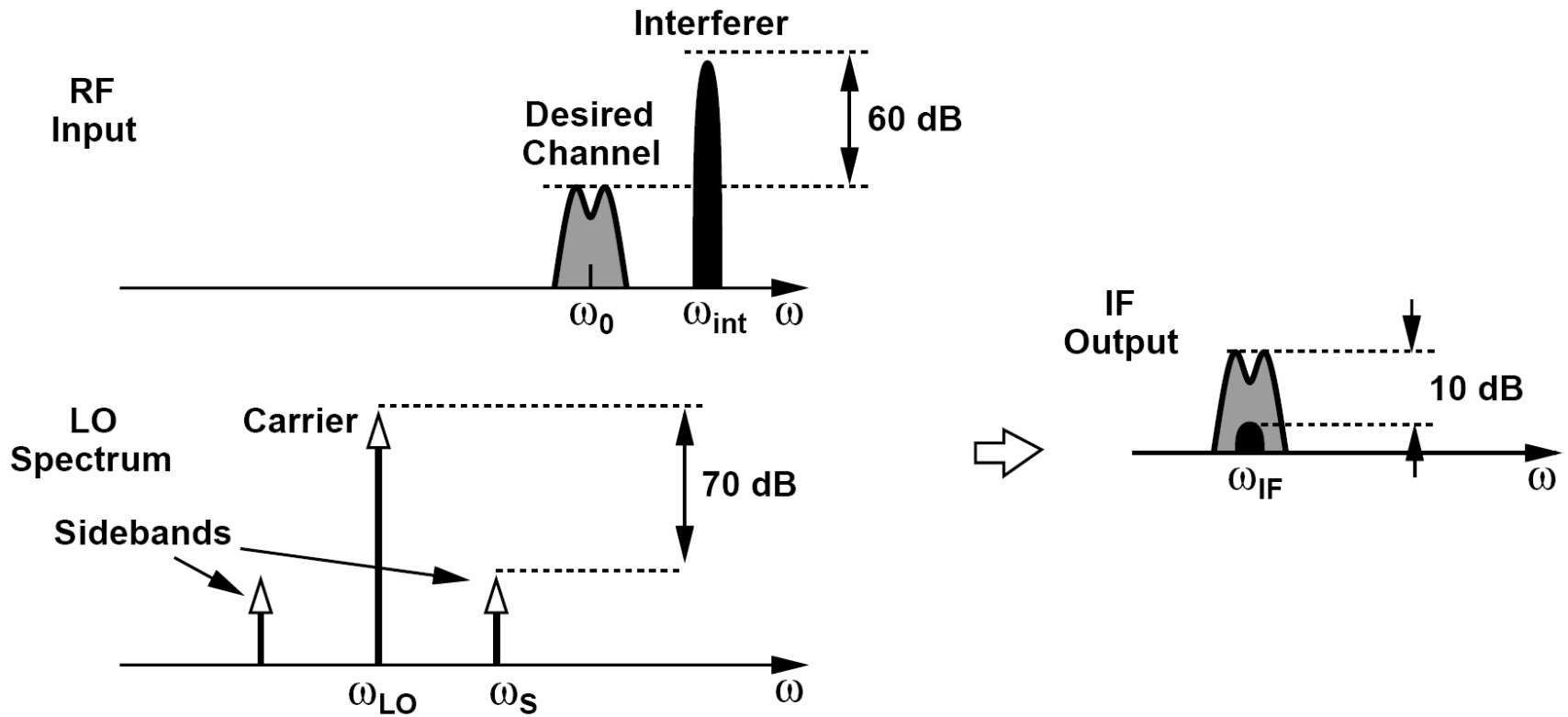
$$\frac{\Delta\omega_{out}}{\omega_{in}} = N \frac{s^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

- If damping factor is  $\sqrt{2}/2$  then the settling time is given by

$$t_s = \frac{\sqrt{2}}{\omega_n} \ln \left| \sqrt{2} \left( 1 - \frac{N_1}{N_2} \right) \frac{1}{\alpha} \right|$$

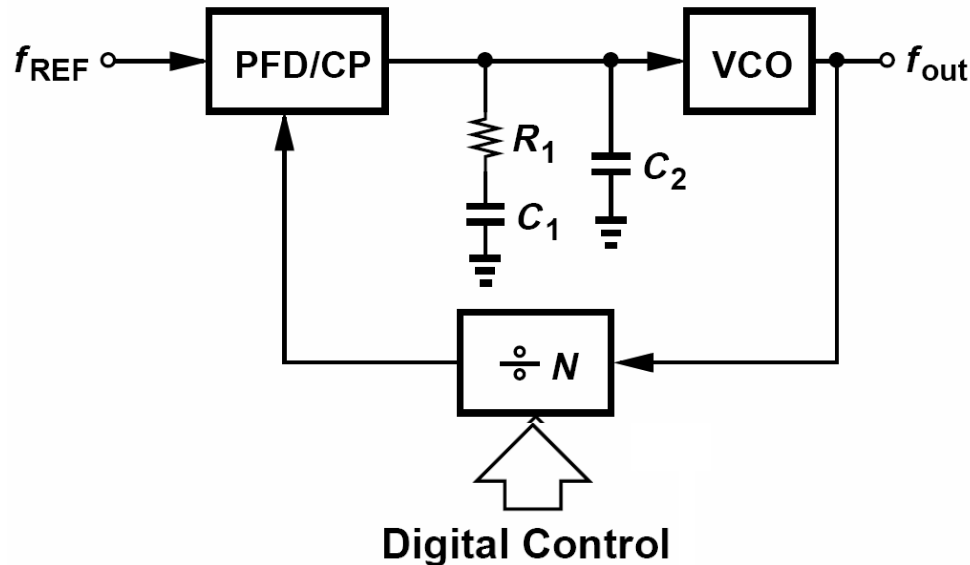
- Causes spillage of TX output power to other channels.
- A well-designed PLL settles in roughly 100 input cycles.

# Sidebands



- Manifests itself in blocking tests and adjacent channel tests.
- Trades with settling time.

# Basic Integer-N Synthesizer



- Frequency channel is assigned by the base station at the beginning of communication.
- Output frequency step = reference frequency
- Example: Find the reference frequency for a Bluetooth receiver using sliding-IF conversion with  $f_{LO} = (2/3)f_{RF}$ .

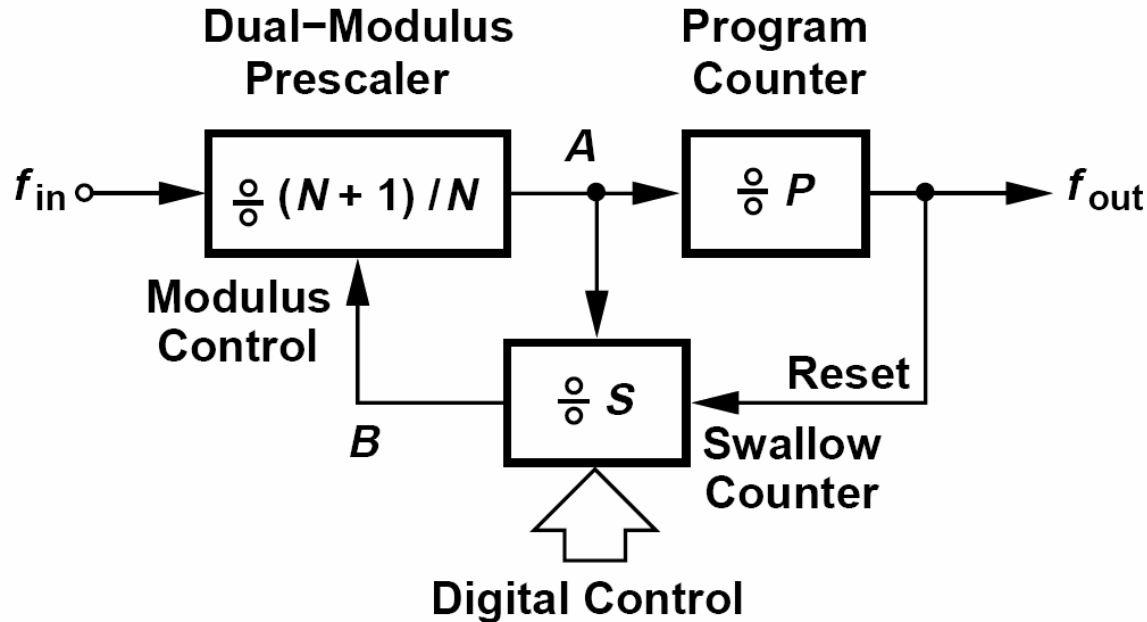


# Integer-N Synthesizer Design

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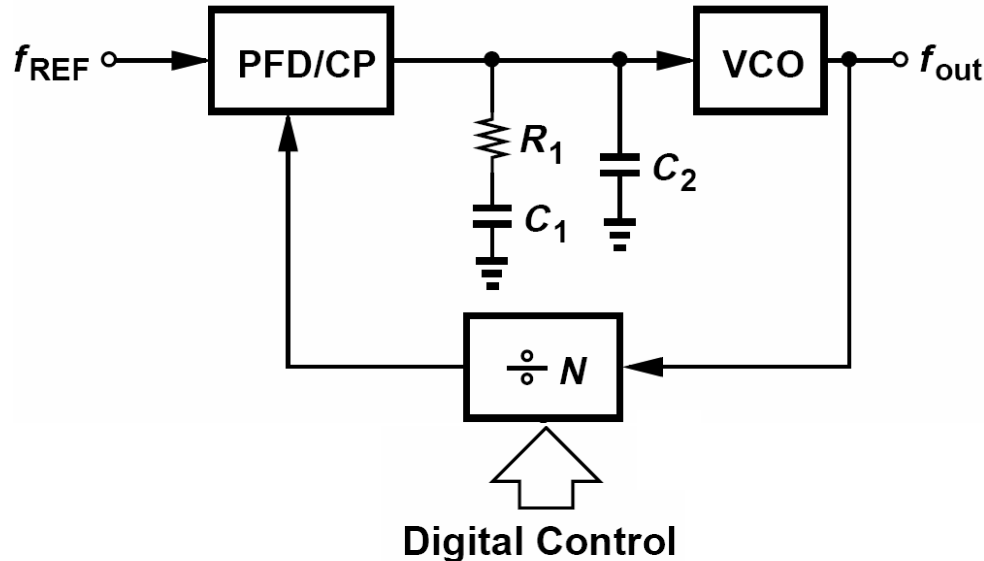
- **VCO**
- **Dual-Modulus Divider**
- **PFD/CP**
- **Loop Filter**
- **Spur Reduction Techniques**
  - **Up/Down Skew Reduction**
  - **Up/Down Current Mismatch Reduction**
  - **Sampling Loop Filter**

# Pulse Swallow Divider



- Prescaler begins with  $N+1$  and counts until swallow counter fills up.
- Prescaler now divides by  $N$  until program counter fills up.

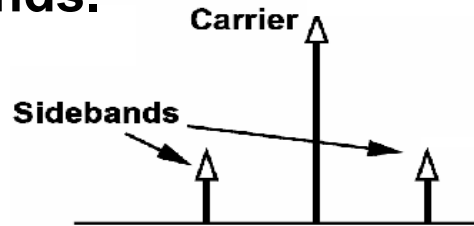
# Drawbacks of Integer-N Synthesizers



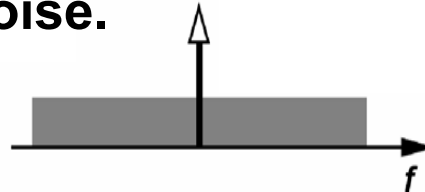
- Output frequency step = reference frequency
- Slow settling if channel spacing is small.
- Little phase noise suppression of VCO if channel spacing is small.
- High amplification of reference phase noise
- Difficult to operate with different crystal frequencies.

# Fractional-N Synthesizers: Preview

- Toggle the divide ratio between  $N$  and  $N+1$  periodically to create an average value equal to  $N+\alpha$ .
- But this modulates the VCO frequency periodically, generating sidebands.



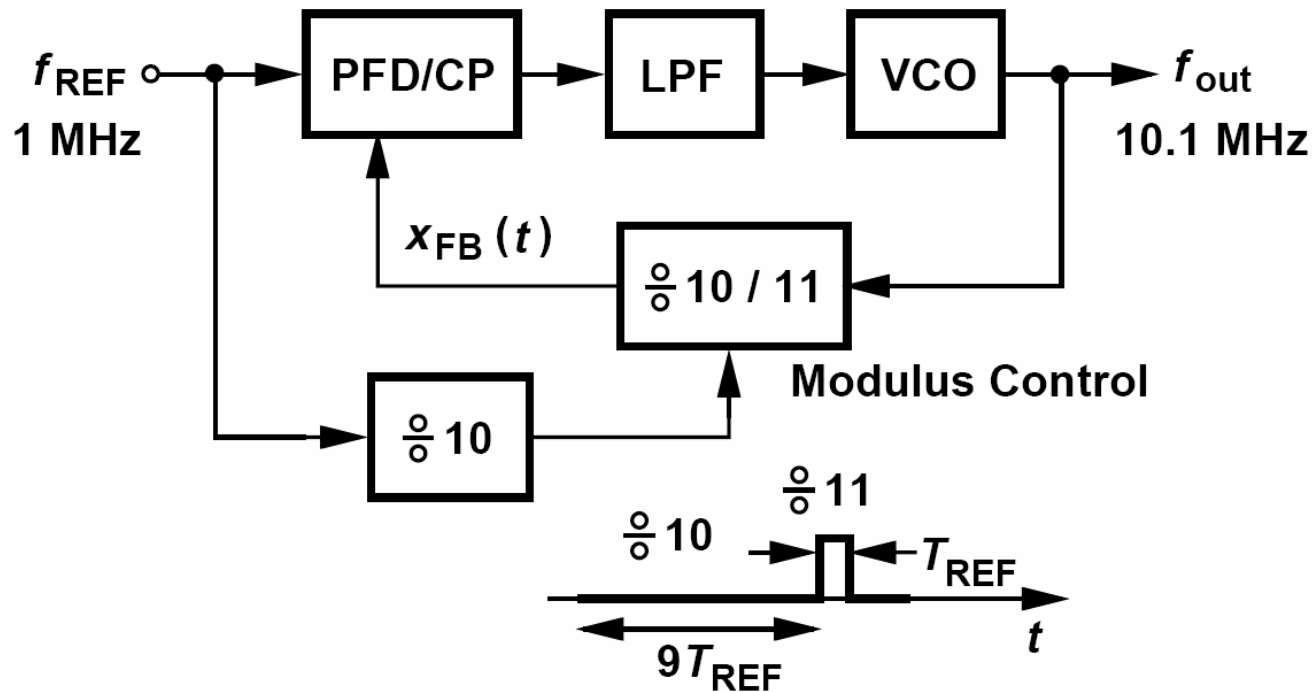
- Toggle the divide ratio between  $N$  and  $N+1$  **randomly** to convert sidebands to noise.



- But the phase noise is now too high.
- “Shape” the spectrum of noise to move its energy to high frequencies, and let the PLL filter out the high-frequency noise.

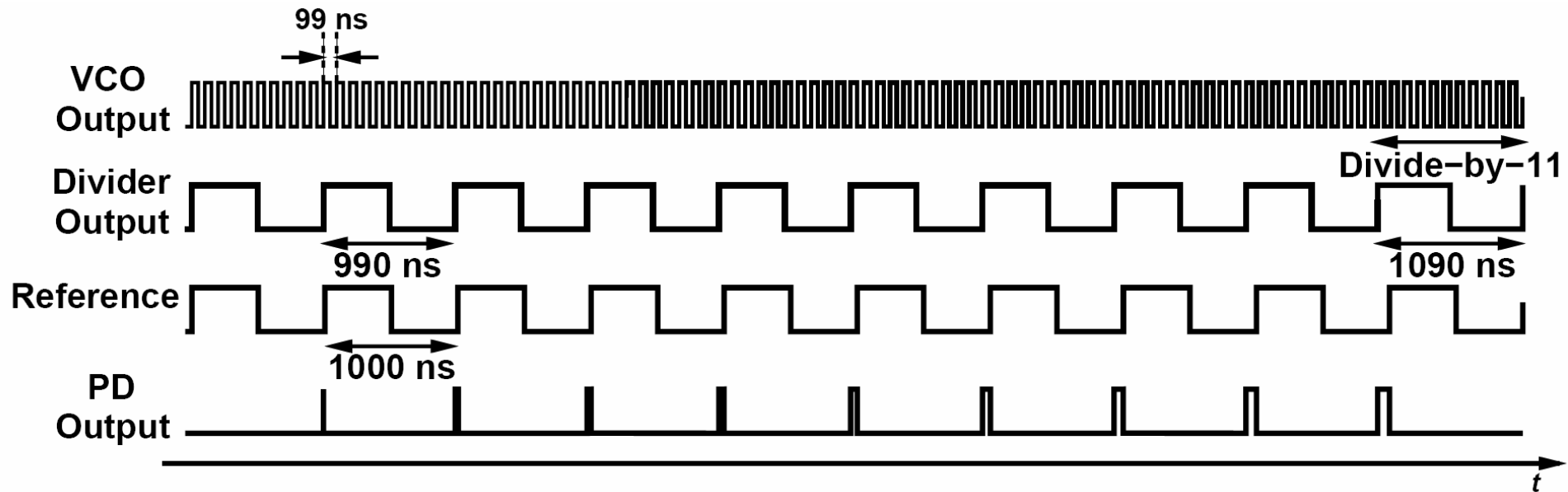


# How to create a fractional divide ratio?



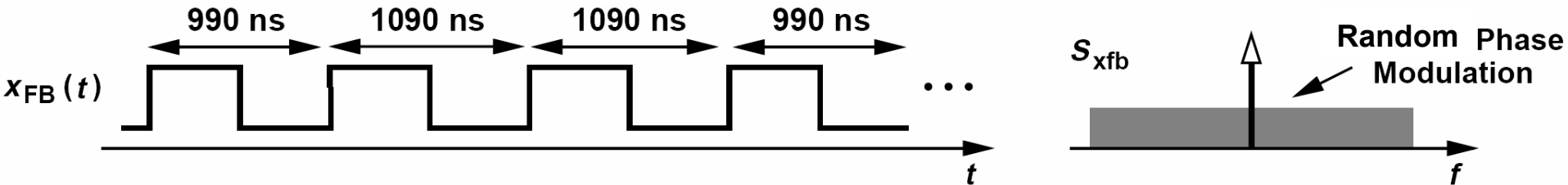
- Decouples output frequency step from the input reference frequency → Wider loop bandwidth →
  - Faster settling
  - Greater VCO phase noise suppression
  - Less amplification of reference phase noise

# Fractional Spurs



- VCO produces sidebands at  $\pm 0.1\text{MHz} \times n$  around 10.1MHz.

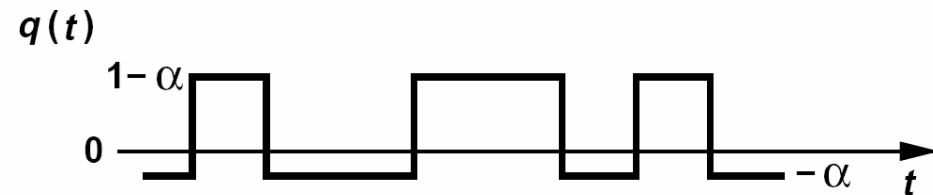
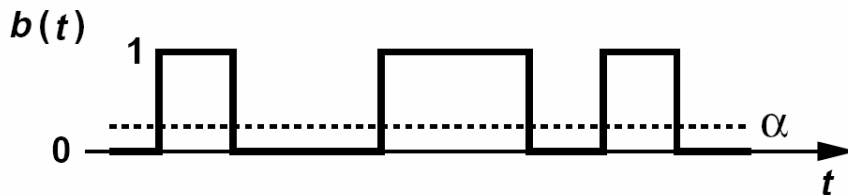
# Conversion of Spurs to Noise



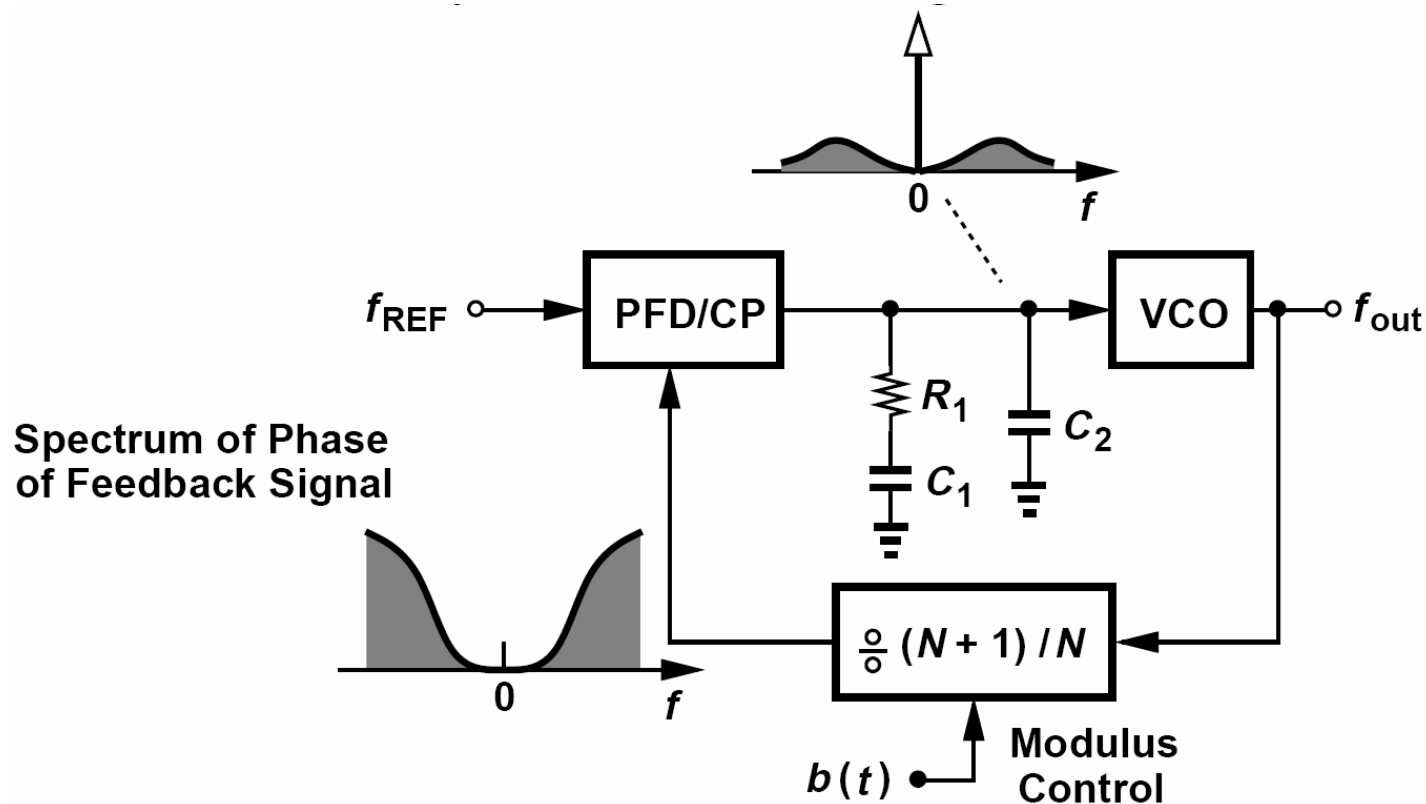
➤ Instantaneous frequency of feedback signal:

$$f_{FB}(t) = \frac{f_{out}}{N + b(t)}$$

$b(t)$  randomly toggles between 0 and 1 and has an average value of  $\alpha$ :



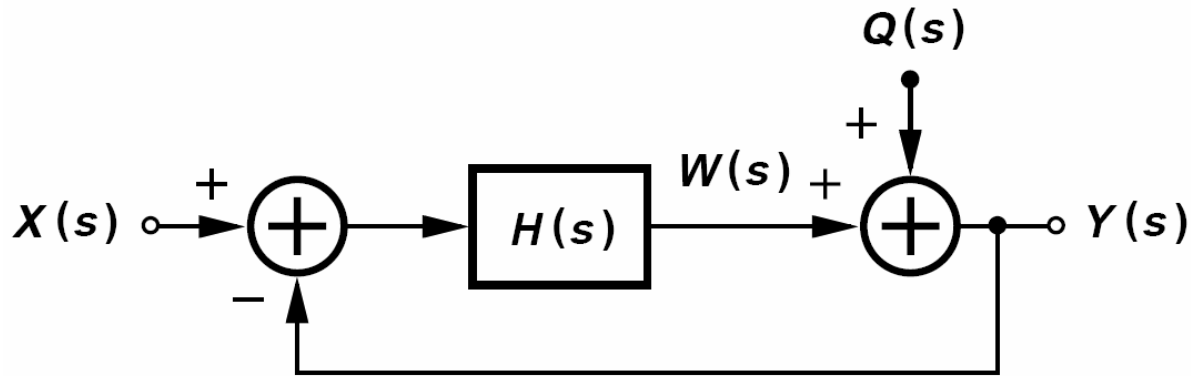
# Basic Noise Shaping



- Generate a random binary sequence,  $b(t)$ , that switches the divider modulus between  $N$  and  $N+1$  such that
  - (1) the average value of the sequence is  $\alpha$ .
  - (2) the noise of the sequence has a **high-pass** spectrum.



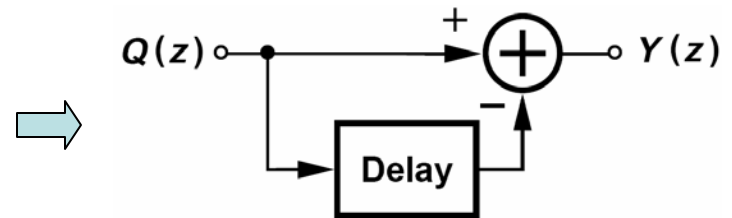
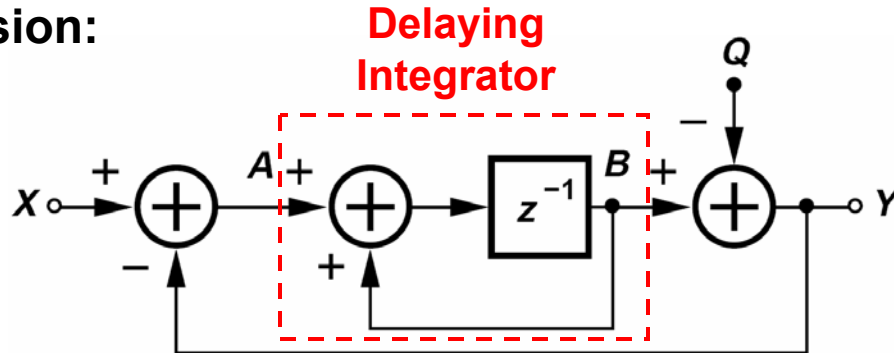
# Negative Feedback System as a High-Pass System



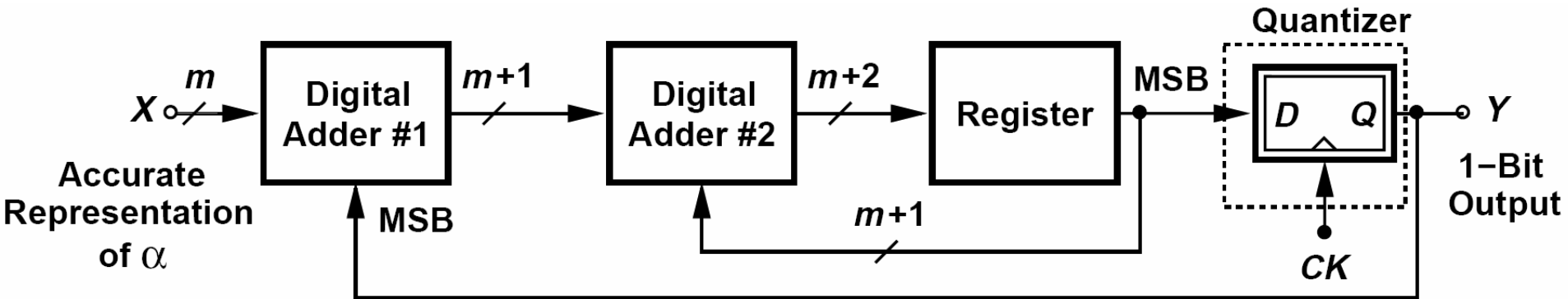
$$\frac{Y(s)}{Q(s)} = \frac{1}{1 + H(s)}$$

If H is an integrator:  $\frac{Y(s)}{Q(s)} = \frac{s}{s + 1}$

Discrete-time version:

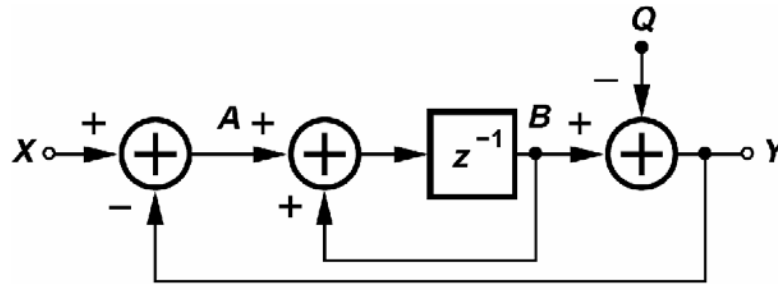


# $\Sigma$ - $\Delta$ Modulator Example



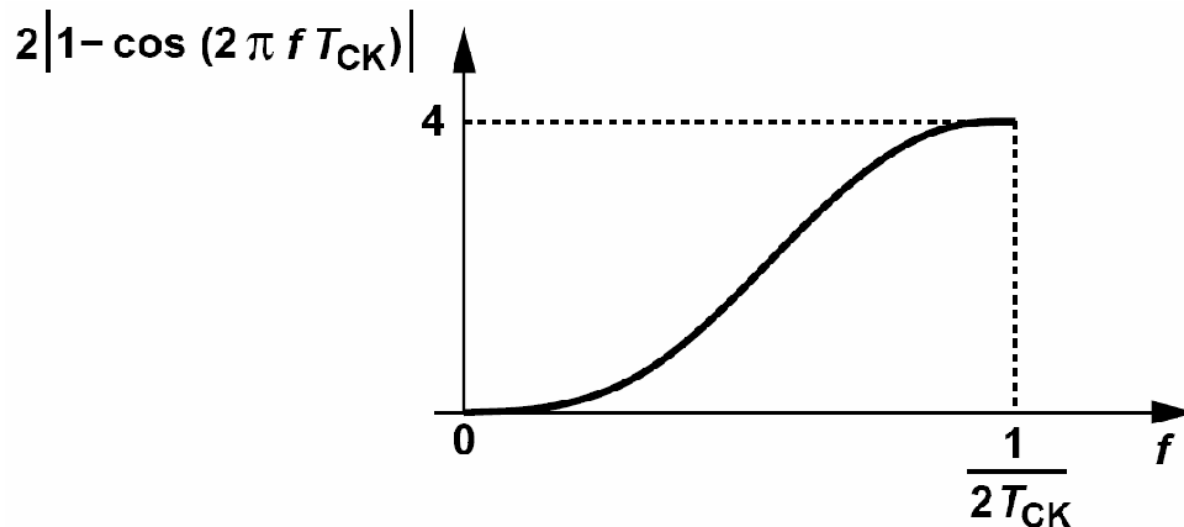
- Quantization from  $m+2$  bits to 1 bit introduces significant noise, but the feedback loop shapes this noise in proportion to  $1-z^{-1}$ .
- Choice of  $m$  is given by the accuracy with which the synthesizer output frequency must be defined.

# Noise Shaping in a $\Sigma\Delta$ Modulator

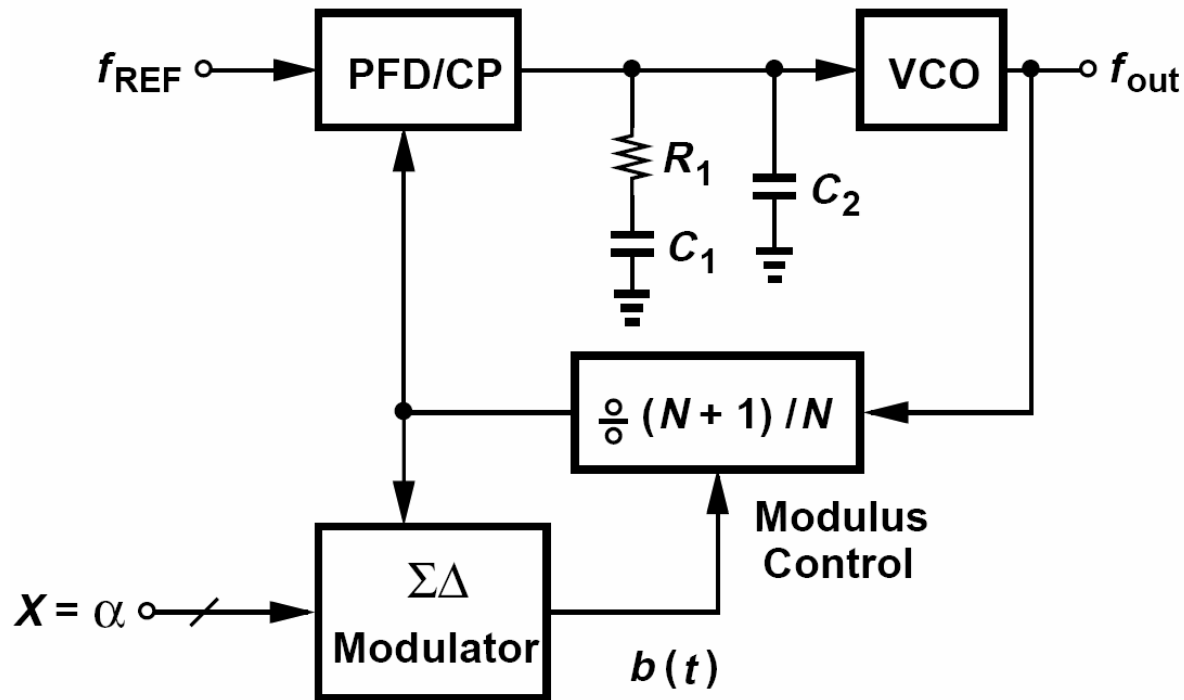


$$\begin{aligned} \frac{Y}{Q}(z) &= 1 - z^{-1} \\ &= e^{-j\pi f T_{CK}} (e^{j\pi f T_{CK}} - e^{-j\pi f T_{CK}}) \\ &= 2j e^{-j\pi f T_{CK}} \sin(\pi f T_{CK}). \end{aligned}$$

Quantization Noise in Output **Frequency**



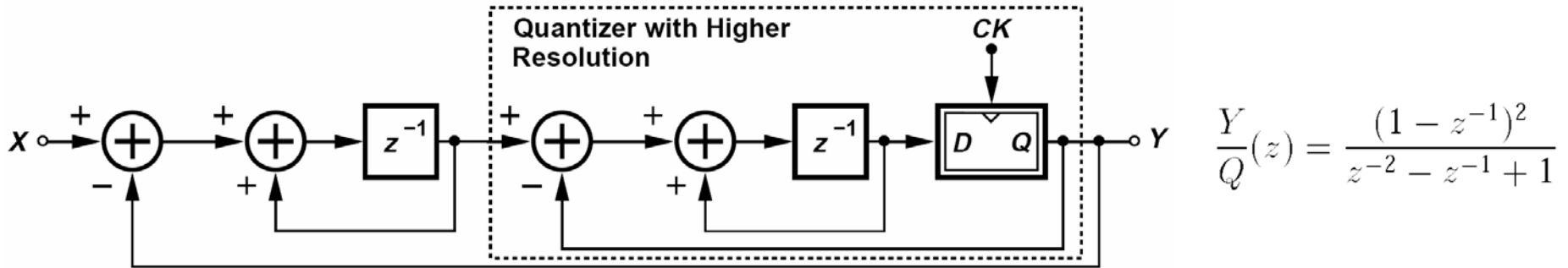
# Basic $\Sigma\Delta$ Fractional-N Synthesizer



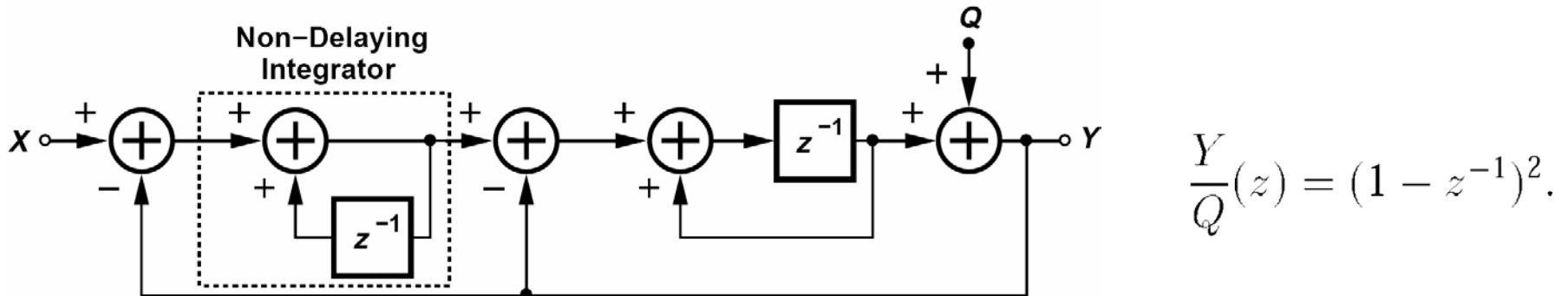
- $\Sigma\Delta$  modulator toggles divide ratio between  $N$  and  $N+1$  so that the average is equal to  $N+\alpha$ .
- Quantization noise in divide ratio is high-pass shaped.

# Higher-Order Noise Shaping

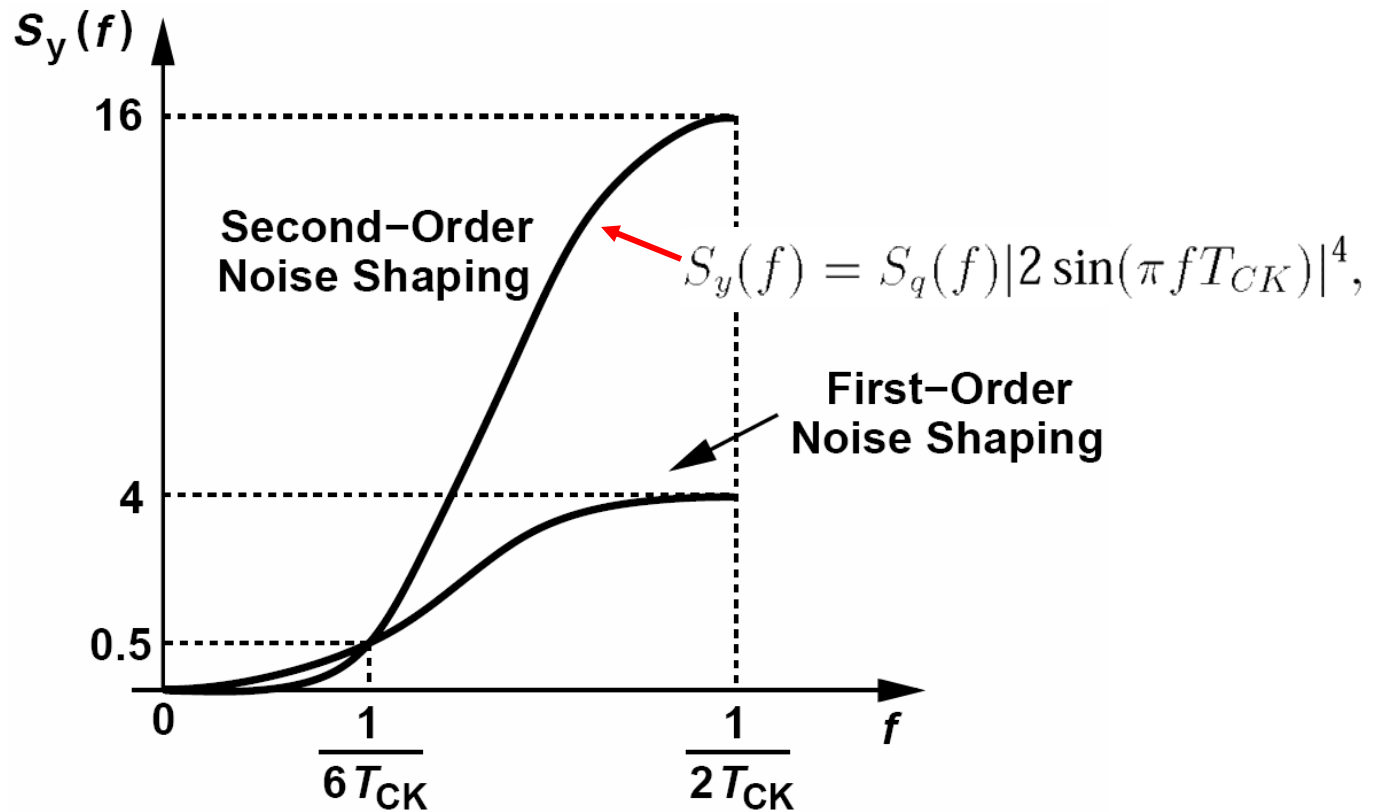
- High-Order Loop: Replace 1-bit quantizer with a finer quantizer:



- Replace delaying integrator with non-delaying integrator:



# Noise Shaping in First- and Second-Order Modulators



# Problem of Out-of-Band Noise

- Transfer function from quantization noise to frequency noise:

$$Y(z) = (1 - z^{-1})^2 Q(z). \quad \leftarrow \text{Second-Order Shaping}$$

$$\Phi(z) = (1 - z^{-1}) Q(z).$$

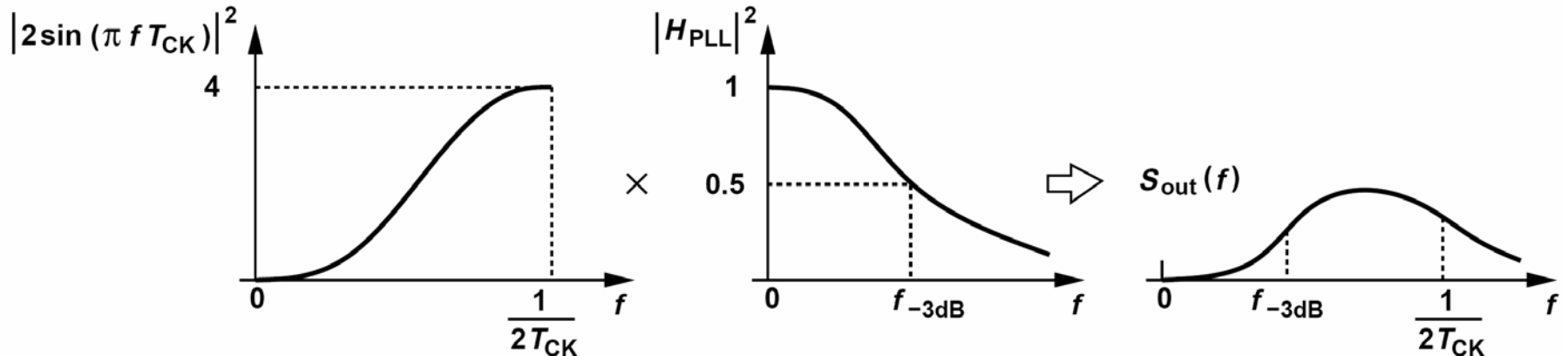
- Spectrum of  $\Sigma\Delta$  phase noise:

$$S_{\Phi}(f) = |1 - z^{-1}|^2 S_q(f)$$

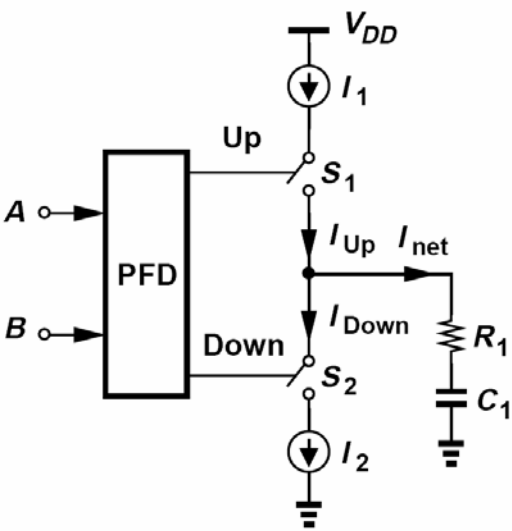
$$= |2 \sin(\pi f T_{CK})|^2 S_q(f).$$

- Spectrum of PLL output phase noise:

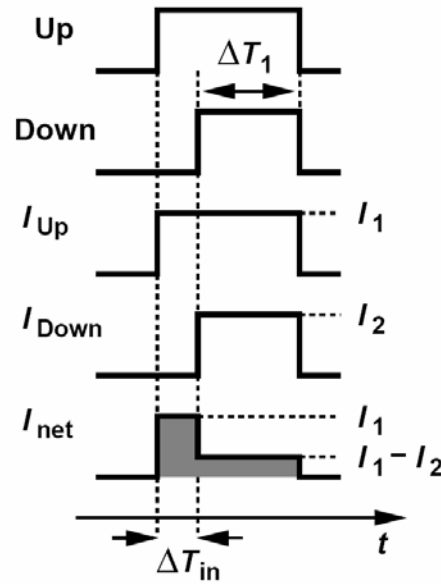
$$S_{out}(f) = |2 \sin(\pi f T_{CK})|^2 S_q(f) N^2 \frac{4\zeta^2 \omega_n^2 \omega^2 + \omega_n^4}{(\omega^2 - \omega_n^2)^2 + 4\zeta^2 \omega_n^2 \omega^2},$$



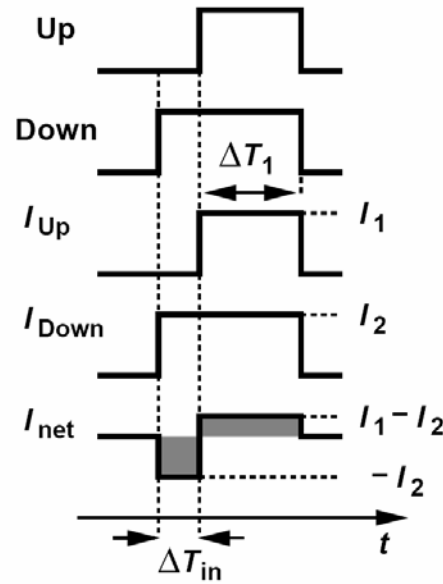
# Nonlinearity Due to Charge Pump Mismatch



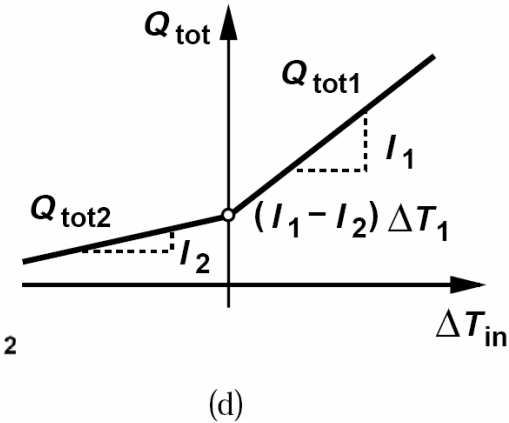
(a)



(b)



(c)



(d)

$(\Delta T_{in}$  is proportional to quantization noise)

- Total charge delivered to the loop filter in (b) is equal to:

$$Q_{tot1} = I_1 \cdot \Delta T_{in} + (I_1 - I_2) \cdot \Delta T_1.$$

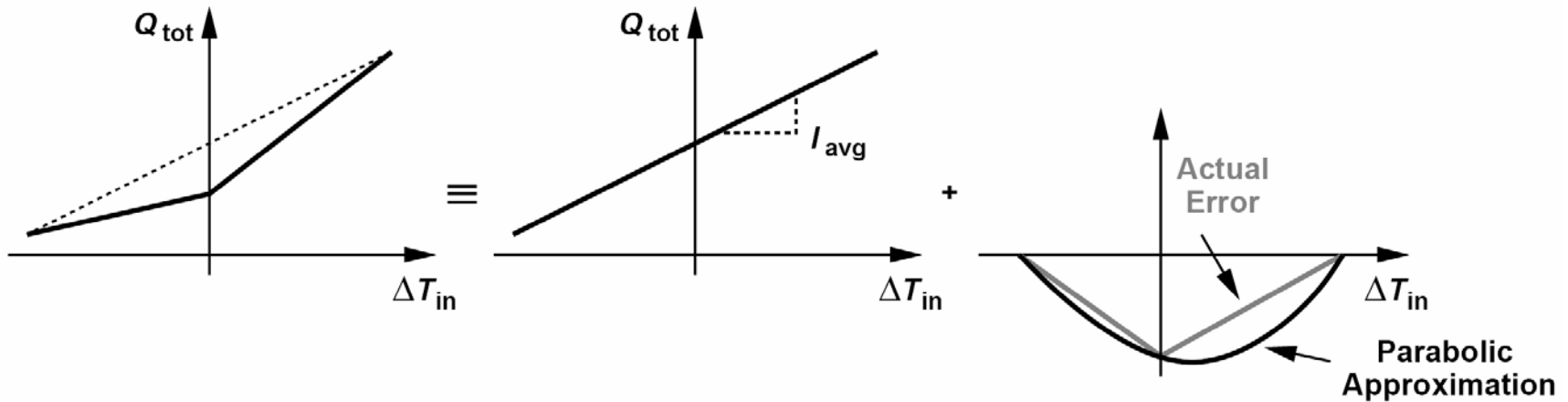
- Now reverse the polarity of the input phase difference:

$$Q_{tot2} = I_2 \cdot \Delta T_{in} + (I_1 - I_2) \Delta T_1.$$

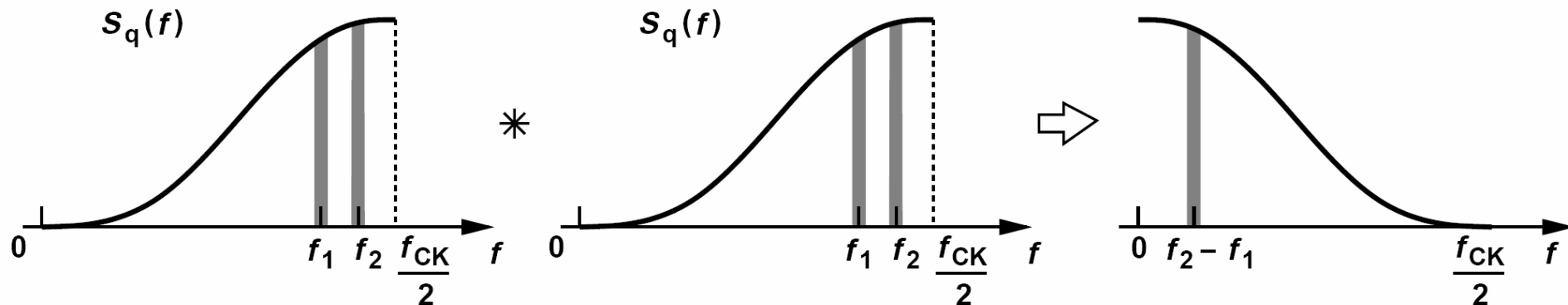
$\Delta T_{in}$  is negative here



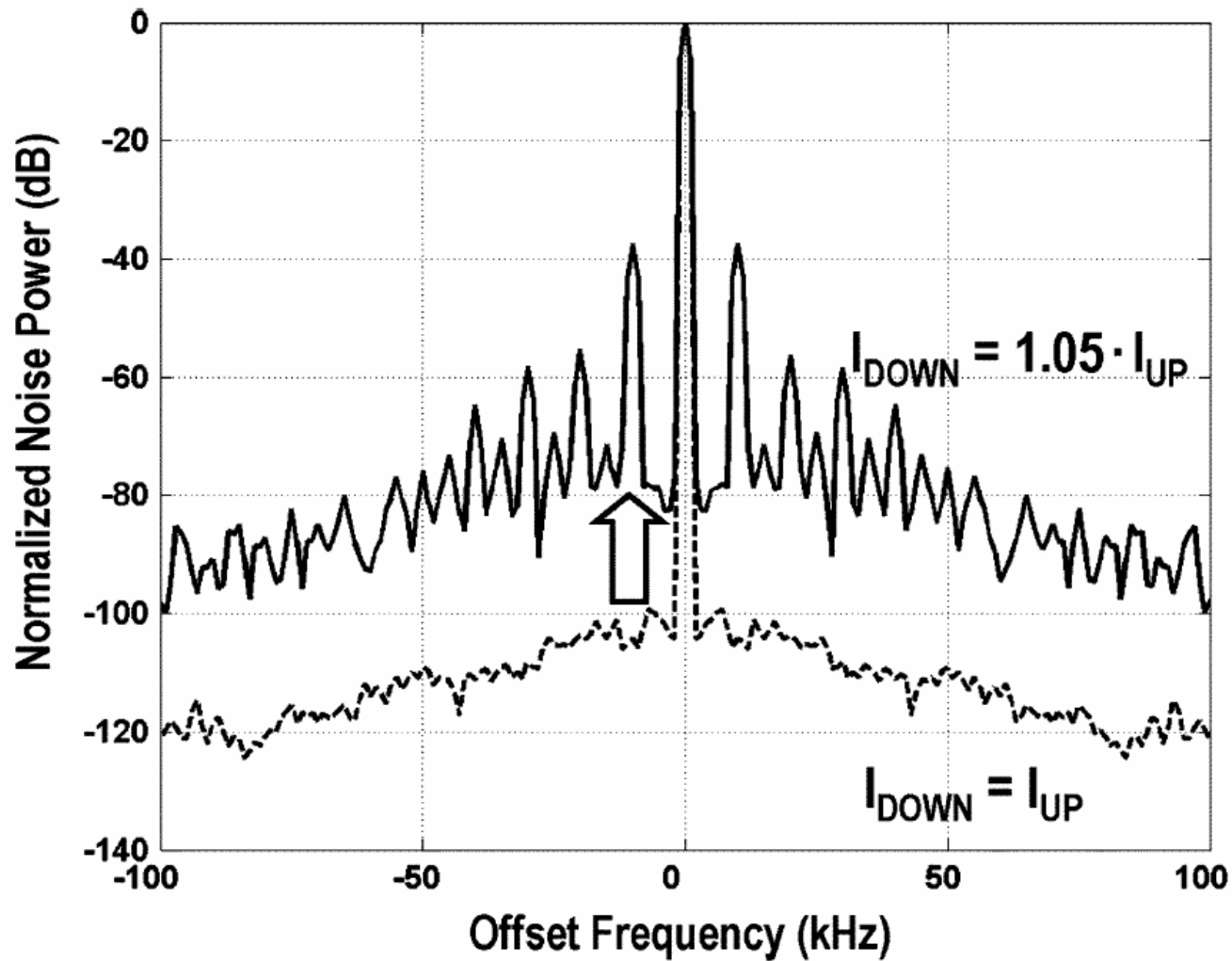
# Effect of Charge Pump Nonlinearity



- Approximate the error by a parabola,  $\alpha\Delta T_{in}^2 - b$ , and write  $Q_{tot} \approx I_{avg}\Delta T_{in} + \alpha\Delta T_{in}^2 - b$
- The multiplication of  $\Delta T_{in}$  by itself is a mixing effect and causes convolution:



# Effect of Charge Pump Nonlinearity



[Huh, JSSC, Nov. 05]