

EE215C

Final Exam

Winter 2013

Name: *Solutions*

Time Limit: 3 Hours
Open Book, Open Notes

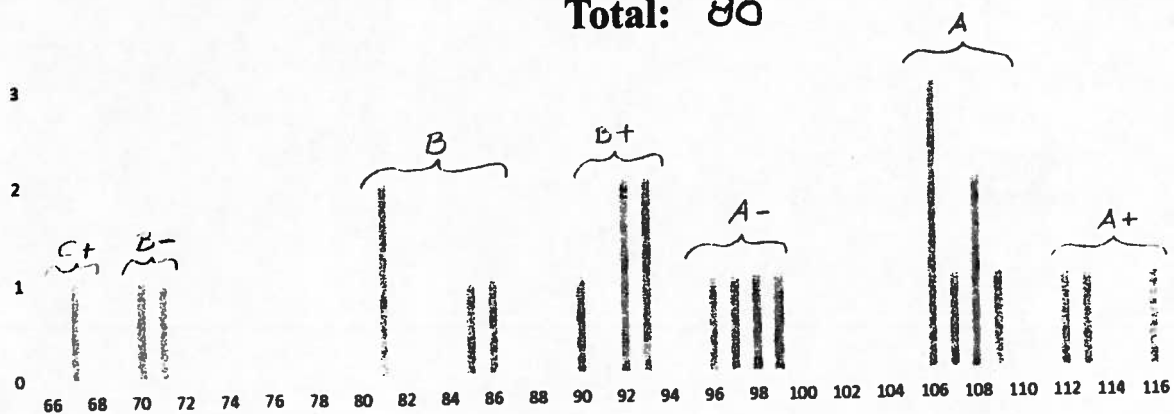
1. 20

2. 20

3. 20

4. 20

Total: 80



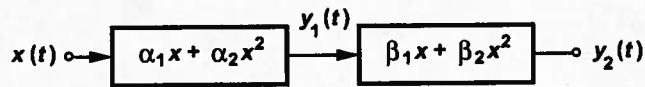
Out of 120

1. Shown below is a cascade of two second-order static systems.

(a) Determine the IIP_3 of the cascade in terms of α_j and β_j .

(b) If each stage is compressive, can the cascade be expansive? Explain in detail.

(c) Is it meaningful to define an IIP_3 for an expansive system? Explain in detail.



$$\begin{aligned} a) \quad y_2(t) &= \beta_1 (\alpha_1 x + \alpha_2 x^2) + \beta_2 (\alpha_1 x + \alpha_2 x^2)^2 \\ &= \underbrace{\alpha_1 \beta_1 x + \alpha_2 \beta_2 x^2}_{k_1} + \underbrace{\alpha_1^2 \beta_2 x^2 + 2 \alpha_1 \alpha_2 \beta_2 x^3 + \alpha_2^2 \beta_2 x^4}_{k_3} \end{aligned}$$

$$A_{IIP3} = \sqrt{\frac{4}{3} \left| \frac{k_1}{k_3} \right|} = \sqrt{\frac{2}{3} \frac{\beta_1}{\alpha_2 \beta_2}}$$

b) Each stage is compressive

$$\rightarrow \alpha_1, \alpha_2 < 0, \quad \beta_1, \beta_2 < 0$$

$$\text{To be expansive, } k_1 \cdot k_3 > 0 \rightarrow \alpha_1 \beta_1 \cdot 2 \alpha_1 \alpha_2 \beta_2 > 0$$

So, if $\alpha_1 > 0$, system can be expandable $\rightarrow \alpha_1 > 0$

c) IIP_3 is still meaningful to define IM_3 components.

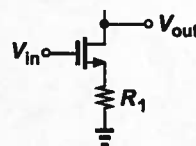
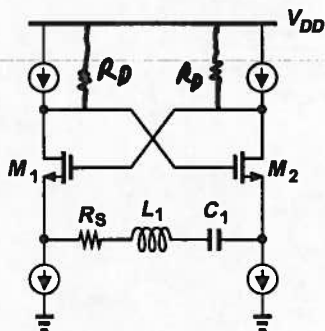
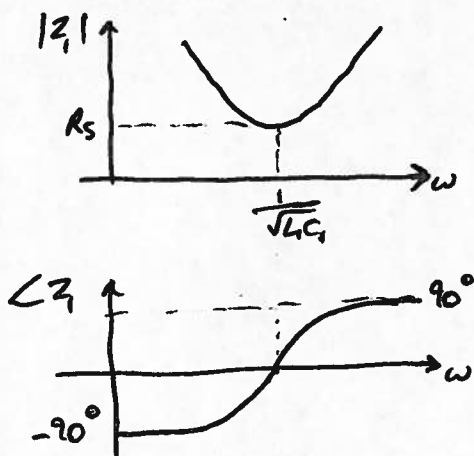
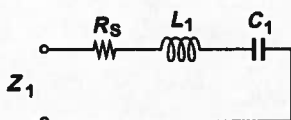
2. In this problem, we investigate an oscillator that incorporates a *series* LC tank.

(a) Consider the series tank shown below, where R_S models the loss of the inductor. Sketch the magnitude and phase of Z_1 as a function of frequency.

(b) Now consider the cross-coupled pair and determine its start-up condition and its frequency of oscillation. Neglect all other capacitances but not channel-length modulation. (~~Hint: first determine the voltage gain of the degenerated stage shown on the right.~~)

a)

$$Z_1 = R_S - j \frac{(1 - L_1 C_1 \omega^2)}{C_1 \omega}$$



$$\Rightarrow Z_{in} = \frac{2V_{GS}}{I_X} = \frac{2(I_D R_D - g_m \gamma_o R_D)}{1 + g_m \gamma_o}$$

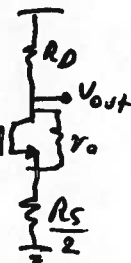
The negative resistance must be stronger than R_S .

$$\Rightarrow \frac{2(\gamma_o R_D - g_m \gamma_o R_D)}{1 + g_m \gamma_o} + R_S < 0$$

if $g_m \gamma_o \gg 1, g_m R_D \gg 1 \Rightarrow -2R_D + R_S < 0$

Another Method is to set the gain of

the circuit on the right greater than 1.



kVL, kCL $\Rightarrow |A_v| = \frac{g_m}{\frac{1}{\gamma_o} + \frac{1}{R_D} + \frac{1}{\gamma_o} \frac{R_S}{2R_D} + \frac{g_m R_S}{2R_D}}$

$$|A_v| > 1 \Rightarrow \frac{g_m \gamma_o R_D}{\gamma_o R_D + \frac{R_S}{2} + \frac{g_m \gamma_o R_S}{2}} > 1$$

$$\Rightarrow \gamma_o R_D - g_m \gamma_o R_D + \frac{R_S}{2} (1 + g_m \gamma_o) < 0$$

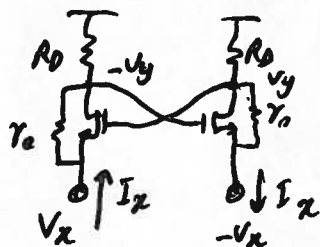
$$\Rightarrow \frac{2(\gamma_o R_D - g_m \gamma_o R_D)}{1 + g_m \gamma_o} + R_S < 0$$

b)

$$f_{osc} = \frac{1}{2\pi \sqrt{L_1 C_1}}$$

To find the start-up condition,

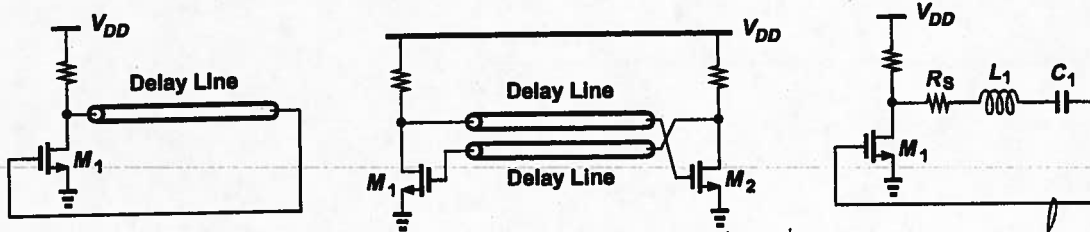
We calculate the impedance seen by the tank.



$$\begin{cases} -V_y = R_D I_x \\ I_x + g_m (V_y - V_x) = \frac{V_x + V_y}{\gamma_o} \end{cases}$$

20.

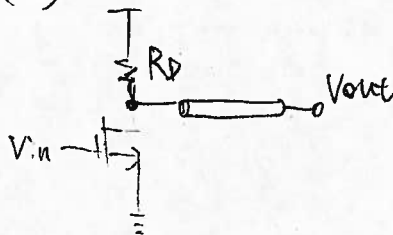
3. Explain in detail which one of the circuits shown below can oscillate. Neglect all other capacitances and channel-length modulation. For the delay lines, you can assume a zero loss, a physical length of l , and a wave velocity of v . If the circuit is capable of oscillation, determine the oscillation frequency.



The delay time of the delay line $T_d = \frac{l}{v}$

Phase introduced by T_d at some $\omega = \frac{T_d}{T} \cdot 2\pi = \omega \cdot T_d$

(A)



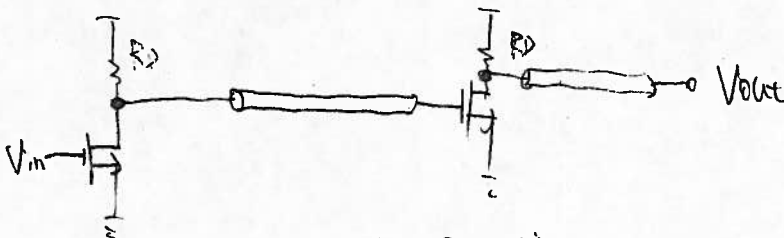
$$|H(s)| = g_m R_D$$

$$\angle H(s) = \omega T_d$$

$$\Rightarrow 2\pi f_{osc} T_d = (2N - 1)\pi$$

$$\Rightarrow f_{osc} = \frac{2N-1}{2T_d} = \frac{(2N-1)V}{2l}, \quad N=1, 2, 3, \dots$$

(B)

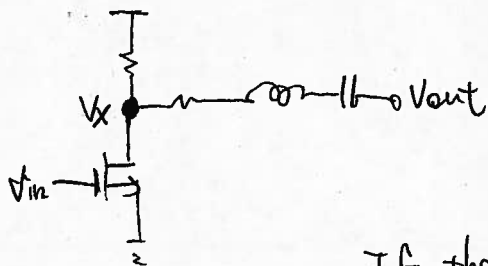


$$|H(s)| = (g_m R_D)^2$$

$$\angle H(s) = \pi + 2\omega T_d \Rightarrow \pi + 2 \cdot 2\pi f_{osc} T_d = \pi + 2 \cdot N \cdot \pi$$

$$\Rightarrow f_{osc} = \frac{N}{2T_d} = \frac{N \cdot V}{2 \cdot l}, \quad N=1, 2, 3, \dots$$

(c)



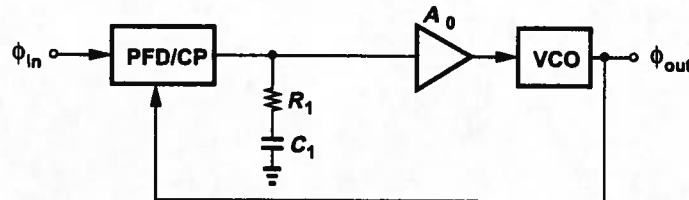
If the gate capacitance is ignored,

$V_x = V_{out}$, $\Rightarrow$ The loop can't provide 360° phase shift, so it can't oscillate.

4. A student decides to precede a VCO in a PLL with an amplifier as shown below. Assume the amplifier has a voltage gain of A_0 .

(a) Suppose the amplifier has an input-referred offset voltage equal to V_{OS} . Does this offset cause a phase error? Explain in detail.

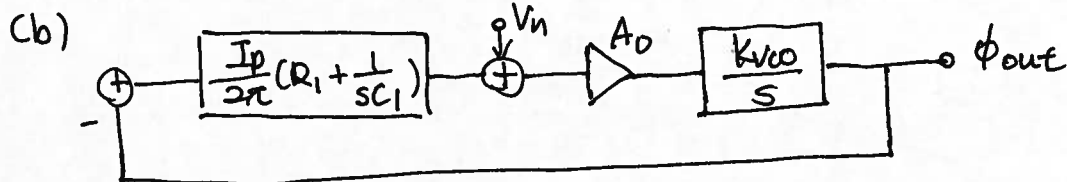
(b) Now suppose the amplifier is free from offset but has noise. Modeling the input-referred noise by a voltage, V_n , find the transfer function from V_n to the output phase. Sketch the magnitude of this transfer function to show its general behavior.



(a) NO, this effect does NOT cause a phase error.

Infinite gain of charge pump and negative feedback force a phase error to be zero with constant V_{OS} .

Another point of view is that DC offset is filtered by the bandpass transfer function of (b).



$$\phi_{out} = (-\phi_{out} \frac{I_p}{2\pi} (R_1 + \frac{1}{sC_1}) + V_n) \times A_0 \times \frac{K_{VCO}}{s}$$

$$\frac{\phi_{out}}{V_n} = \frac{A_0 K_{VCO} s}{s^2 + A_0 K_{VCO} R_1 \frac{I_p}{2\pi} s + A_0 K_{VCO} \frac{I_p}{2\pi C_1}}$$

