7. Linear equations

- QR factorization method
- factor and solve
- LU factorization

QR factorization and matrix inverse

QR factorization of nonsingular matrix

every nonsingular $A \in \mathbf{R}^{n\times n}$ has a QR factorization

$$A = QR$$

- $Q \in \mathbf{R}^{n\times n}$ is orthogonal ($Q^TQ = QQ^T = I$)
- $R \in \mathbf{R}^{n\times n}$ is upper triangular with positive diagonal elements

Inverse from QR factorization: the inverse A^{-1} can be written as

$$A^{-1} = (QR)^{-1} = R^{-1}Q^{-1} = R^{-1}Q^T$$

Solving linear equations by QR factorization

Algorithm: to solve $Ax = b$ with nonsingular $A \in \mathbf{R}^{n \times n}$,

1. factor A as $A = QR$
2. compute $y = Q^T b$
3. solve $Rx = y$ by back substitution

Complexity: $2n^3 + 3n^2 \sim 2n^3$ flops

- QR factorization: $2n^3$
- matrix–vector multiplication: $2n^2$
- back substitution: n^2

Multiple right-hand sides

consider k sets of linear equations with the same coefficient matrix A:

$$Ax_1 = b_1, \qquad Ax_2 = b_2, \qquad \ldots, \qquad Ax_k = b_k$$

- equivalently, solve $AX = B$ where B is $n \times k$ matrix with columns $b_1, \ldots, b_k$
- can be solved in $2n^3 + 3kn^2$ flops if we reuse the factorization $A = QR$
- for $k \ll n$, cost is roughly equal to cost of solving one equation ($2n^3$)

Application: to compute A^{-1}, solve the matrix equation $AX = I$

- equivalent to n equations

$$Rx_1 = Q^T e_1, \qquad Rx_2 = Q^T e_2, \qquad \ldots, \qquad Rx_n = Q^T e_n$$

  (x_i is column i of X and $Q^T e_i$ is transpose of ith row of Q)
- complexity is $2n^3 + n^3 = 3n^3$ (here the 2nd term n^3 is not negligible)

Outline

- QR factorization method
- **factor and solve**
- LU factorization

Factor–solve approach

to solve $Ax = b$, first write A as a product of "simple" matrices

$$A = A_1 A_2 \cdots A_k$$

then solve $(A_1 A_2 \cdots A_k)x = b$ by solving k equations

$$A_1 z_1 = b, \qquad A_2 z_2 = z_1, \qquad \ldots, \qquad A_{k-1} z_{k-1} = z_{k-2}, \qquad A_k x = z_{k-1}$$

Examples

- QR factorization: $k = 2$, $A = QR$
- LU factorization (this lecture)
- Cholesky factorization (later)

Complexity of factor–solve method

$$\#\text{flops} = f + s$$

- f is complexity of factoring A as $A = A_1 A_2 \cdots A_k$ (factorization step)
- s is complexity of solving the k equations for $z_1, z_2, \ldots z_{k-1}, x$ (solve step)
- usually $f \gg s$

Example: solving linear equations using the QR factorization

$$f = 2n^3, \qquad s = 3n^2$$

Outline

- QR factorization method
- factor and solve
- **LU factorization**

LU factorization

LU factorization without pivoting

$$A = LU$$

- L unit lower triangular, U upper triangular
- does not always exist (even if A is nonsingular)

LU factorization (with row pivoting)

$$A = PLU$$

- P permutation matrix, L unit lower triangular, U upper triangular
- exists if and only if A is nonsingular (see later)

Complexity: $\frac{2}{3}n^3$ if A is $n \times n$

Solving linear equations by LU factorization

Algorithm: to solve $Ax = b$ with nonsingular A of size $n \times n$

1. factor A as $A = PLU$ ($\frac{2}{3}n^3$ flops)
2. solve $(PLU)x = b$ in three steps
   (a) permutation: $z_1 = P^T b$ (0 flops)
   (b) forward substitution: solve $Lz_2 = z_1$ (n^2 flops)
   (c) back substitution: solve $Ux = z_2$ (n^2 flops)

Complexity: $\frac{2}{3}n^3 + 2n^2 \sim \frac{2}{3}n^3$ flops

this is the standard method for solving $Ax = b$

Multiple right-hand sides

two equations with the same matrix A (nonsingular and $n \times n$):

$$Ax = b, \qquad A\tilde{x} = \tilde{b}$$

- factor A once
- forward/back substitution to get x
- forward/back substitution to get $\tilde{x}$

complexity: $\frac{2}{3}n^3 + 4n^2 \sim \frac{2}{3}n^3$

Exercise: propose an efficient method for solving

$$Ax = b, \qquad A^T\tilde{x} = \tilde{b}$$

LU factorization and matrix inverse

suppose A is nonsingular and $n \times n$, with LU factorization

$$A = PLU$$

- inverse from LU factorization

$$A^{-1} = (PLU)^{-1} = U^{-1}L^{-1}P^T$$

- gives interpretation of solve step: we evaluate

$$x = A^{-1}b = U^{-1}L^{-1}P^Tb$$

  in three steps

$$z_1 = P^Tb, \qquad z_2 = L^{-1}z_1, \qquad x = U^{-1}z_2$$

Computing the inverse

solve $AX = I$ column by column

- one LU factorization of A: $\frac{2}{3}n^3$ flops
- n solve steps: $2n^3$ flops
- total: $\frac{8}{3}n^3$ flops

slightly faster methods exist that exploit structure in right-hand side I

Conclusion: do not solve $Ax = b$ by multiplying A^{-1} with b

LU factorization without pivoting

$$\begin{bmatrix} A_{11} & A_{1,2:n} \\ A_{2:n,1} & A_{2:n,2:n} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ L_{2:n,1} & L_{2:n,2:n} \end{bmatrix} \begin{bmatrix} U_{11} & U_{1,2:n} \\ 0 & U_{2:n,2:n} \end{bmatrix}$$

$$= \begin{bmatrix} U_{11} & U_{1,2:n} \\ U_{11}L_{2:n,1} & L_{2:n,1}U_{1,2:n} + L_{2:n,2:n}U_{2:n,2:n} \end{bmatrix}$$

Recursive algorithm

- determine first row of U and first column of L

$$U_{11} = A_{11}, \qquad U_{1,2:n} = A_{1,2:n}, \qquad L_{2:n,1} = \frac{1}{A_{11}} A_{2:n,1}$$

- factor the $(n-1) \times (n-1)$-matrix $A_{2:n,2:n} - L_{2:n,1}U_{1,2:n}$ as

$$A_{2:n,2:n} - L_{2:n,1}U_{1,2:n} = L_{2:n,2:n}U_{2:n,2:n}$$

  this is an LU factorization (without pivoting) of size $(n-1) \times (n-1)$

Example

LU factorization (without pivoting) of

$$A = \begin{bmatrix} 8 & 2 & 9 \\ 4 & 9 & 4 \\ 6 & 7 & 9 \end{bmatrix}$$

write as $A = LU$ with L unit lower triangular, U upper triangular

$$A = \begin{bmatrix} 8 & 2 & 9 \\ 4 & 9 & 4 \\ 6 & 7 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ L_{21} & 1 & 0 \\ L_{31} & L_{32} & 1 \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

Example

- first row of U, first column of L:

$$\begin{bmatrix} 8 & 2 & 9 \\ 4 & 9 & 4 \\ 6 & 7 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 3/4 & L_{32} & 1 \end{bmatrix} \begin{bmatrix} 8 & 2 & 9 \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

- second row of U, second column of L:

$$\begin{bmatrix} 9 & 4 \\ 7 & 9 \end{bmatrix} - \begin{bmatrix} 1/2 \\ 3/4 \end{bmatrix} \begin{bmatrix} 2 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ L_{32} & 1 \end{bmatrix} \begin{bmatrix} U_{22} & U_{23} \\ 0 & U_{33} \end{bmatrix}$$

$$\begin{bmatrix} 8 & -1/2 \\ 11/2 & 9/4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 11/16 & 1 \end{bmatrix} \begin{bmatrix} 8 & -1/2 \\ 0 & U_{33} \end{bmatrix}$$

- third row of U: $U_{33} = 9/4 + 11/32 = 83/32$

Conclusion

$$A = \begin{bmatrix} 8 & 2 & 9 \\ 4 & 9 & 4 \\ 6 & 7 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 3/4 & 11/16 & 1 \end{bmatrix} \begin{bmatrix} 8 & 2 & 9 \\ 0 & 8 & -1/2 \\ 0 & 0 & 83/32 \end{bmatrix}$$

Not every nonsingular A can be factored as $A = LU$

$$A = \begin{bmatrix} 2 & -2 & 0 \\ -1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ L_{21} & 1 & 0 \\ L_{31} & L_{32} & 1 \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

- first row of U, first column of L:

$$\begin{bmatrix} 2 & -2 & 0 \\ -1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1/2 & 1 & 0 \\ 1/2 & L_{32} & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 & 0 \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

- second row of U, second column of L:

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} -1/2 \\ 1/2 \end{bmatrix} \begin{bmatrix} -2 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ L_{32} & 1 \end{bmatrix} \begin{bmatrix} U_{22} & U_{23} \\ 0 & U_{33} \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ ?? & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & U_{33} \end{bmatrix}$$

the matrix A is nonsingular, but no factorization $A = LU$ exists

LU factorization (with row pivoting)

if A is $n \times n$ and nonsingular, then it can be factored as

$$A = PLU$$

P is a permutation matrix, L is unit lower triangular, U is upper triangular

- not unique; there may be several possible choices for P, L, U
- interpretation: permute the rows of A and factor $P^T A$ as $P^T A = LU$
- also known as *Gaussian elimination with partial pivoting* (GEPP)
- complexity: $\frac{2}{3}n^3$ flops

we skip the details of calculating P, L, U

Example

$$\begin{bmatrix} 0 & 5 & 5 \\ 2 & 9 & 0 \\ 6 & 8 & 8 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1/3 & 1 & 0 \\ 0 & 15/19 & 1 \end{bmatrix} \begin{bmatrix} 6 & 8 & 8 \\ 0 & 19/3 & -8/3 \\ 0 & 0 & 135/19 \end{bmatrix}$$

the factorization is not unique; the same matrix can be factored as

$$\begin{bmatrix} 0 & 5 & 5 \\ 2 & 9 & 0 \\ 6 & 8 & 8 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & -19/5 & 1 \end{bmatrix} \begin{bmatrix} 2 & 9 & 0 \\ 0 & 5 & 5 \\ 0 & 0 & 27 \end{bmatrix}$$

Effect of rounding error

$$\begin{bmatrix} 10^{-5} & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

solution:

$$x_1 = \frac{-1}{1 - 10^{-5}}, \qquad x_2 = \frac{1}{1 - 10^{-5}}$$

- let us solve using LU factorization for the two possible permutations:

$$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{or} \quad P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- we round intermediate results to four significant decimal digits

First choice: $P = I$ (no pivoting)

$$\begin{bmatrix} 10^{-5} & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 10^5 & 1 \end{bmatrix} \begin{bmatrix} 10^{-5} & 1 \\ 0 & 1 - 10^5 \end{bmatrix}$$

- L, U rounded to 4 significant decimal digits

$$L = \begin{bmatrix} 1 & 0 \\ 10^5 & 1 \end{bmatrix}, \qquad U = \begin{bmatrix} 10^{-5} & 1 \\ 0 & -10^5 \end{bmatrix}$$

- forward substitution

$$\begin{bmatrix} 1 & 0 \\ 10^5 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \Longrightarrow \quad z_1 = 1, \quad z_2 = -10^5$$

- back substitution

$$\begin{bmatrix} 10^{-5} & 1 \\ 0 & -10^5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ -10^5 \end{bmatrix} \quad \Longrightarrow \quad x_1 = 0, \quad x_2 = 1$$

error in x_1 is 100%

Second choice: interchange rows

$$\begin{bmatrix} 1 & 1 \\ 10^{-5} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 10^{-5} & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 - 10^{-5} \end{bmatrix}$$

- L, U rounded to 4 significant decimal digits

$$L = \begin{bmatrix} 1 & 0 \\ 10^{-5} & 1 \end{bmatrix}, \qquad U = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

- forward substitution

$$\begin{bmatrix} 1 & 0 \\ 10^{-5} & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad \Longrightarrow \qquad z_1 = 0, \quad z_2 = 1$$

- backward substitution

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad \Longrightarrow \qquad x_1 = -1, \quad x_2 = 1$$

error in x_1, x_2 is about 10^{-5}

Conclusion: rounding error and LU factorization

- for certain P, small errors in the algorithm can cause large errors in the solution
- this is called *numerical instability:* for the first choice of P in the example, the algorithm is unstable; for the second choice of P, it is stable
- from numerical analysis: there is a simple rule for selecting a good permutation

  (we skip the details, since we skipped the details of the factorization)

Sparse linear equations

if A is sparse, it is usually factored as

$$A = P_1 L U P_2$$

P_1 and P_2 are permutation matrices

- interpretation: permute rows and columns of A and factor $\tilde{A} = P_1^T A P_2^T$

$$\tilde{A} = LU$$

- choice of P_1 and P_2 greatly affects the sparsity of L and U
- several heuristic methods exist for selecting good permutations
- in practice: #flops $\ll \frac{2}{3}n^3$
- exact value depends on n, number of nonzero elements, sparsity pattern

Conclusion

different levels of detail in understanding how linear equation solvers work

High level

- `x = A \ b` costs $\frac{2}{3}n^3$
- more efficient than `x = inv(A) * b`

Intermediate level: factorization step $A = PLU$ followed by solve step

Detailed level: computation of factorization $A = PLU$

- for most applications, level 1 is sufficient
- in some situations (*e.g.*, multiple right-hand sides) level 2 is useful
- level 3 is important for experts who write numerical software libraries